# LORD DATASHEET

# 3DM<sup>™</sup>-CV5<sup>™</sup>-10

# **Inertial Measurement Unit (IMU)**

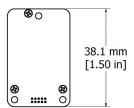


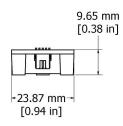
3DM-CV5-10 - miniature, industrial-grade inertial measurement unit (IMU)

The LORD Sensing 3DM-CV5 family of industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial measurements and computed attitude and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration and angular rate, and are fully temperature- compensated and calibrated over the operating temperature. The use of Micro- Electro- Mechanical System (MEMS) technology allows for highly accurate, small, lightweight devices.

The LORD Sensing **MIP Monitor** software can be used for device configuration, live data monitoring, and recording. Alternatively, the **MIP Data Communications Protocol** is available for development of custom interfaces and easy OEM integration.





#### **Product Highlights**

- Triaxial accelerometer, gyroscope, and temperature sensors achieve the optimal combination of measurement qualities
- Smallest, lightest, highest performance IMU in its class

#### **Features and Benefits**

#### Best in Class Performance

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- · High-performance, low-cost solution
- Direct PCB mount or chassis mount with ribbon cable
- · Precision mounting alignment features

#### Ease of Use

- Easy integration via comprehensive and fully backwardscompatible communication protocol
- · Robust, forward compatible MIP packet protocol

#### Cost Effective

- · Out-of-the box solution reduces development time
- Volume discounts

### **Applications**

- · Platform stabilization, artificial horizon
- · Health and usage monitoring of vehicles

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# **Specifications**

General			
Triaxial accelerometer, triaxial gyroscope, and			
Integrated sensors	temperature sensors		
	Inertial Measurement Unit (IMU) outputs: acceleration,		
Data outputs	angular rate, delta theta, o	delta velocity	
Inertial Measurement Unit (IMU) Sensor Outputs			
	Accelerometer	Gyroscope	
		±500°/sec (standard) ±250°. ±1000°/sec	
Measurement range	±8 g (standard)	,	
	±2 g, ±4 g (optional)	(optional)	
Non-linearity	±0.04% fs	0.06% fs	
Bias instability	±0.04 mg	8°/hr	
Initial bias error	±0.004 g	0.1°/sec	
Scale factor stability	±0.05%	±0.05%	
Noise density	100 μg/√Hz	0.0075°/sec/√Hz	
		(300°/sec)	
Alignment error	±0.05°	±0.05°	
Adjustable bandwidth	500 Hz (max)	500 Hz (max)	
Offset error over temperature	0.2% (typ)	0.1% (typ)	
Gain error over	0.05% (typ)	0.06% (typ)	
temperature	(31)	(31)	
Scale factor non-	0.04% (typ)	0.04% (typ)	
linearity	0.2% (max)	0.15% (max)	
(@ 25° C)	Digital averaging filter (uppredigetable) compled at 2		
IMU filtering	Digital averaging filter (user adjustable) sampled at 2 kHz and scaled into physical units; coning and sculling		
IIIIO IIIIGIIIIG	integrals computed at 1 kHz		
Sampling rate	2 kHz	2 kHz	
IMU data output rate	1 Hz to 1000 Hz	1	
Pressure Sensor			
Range	260 to 1260 hPa		
Resolution	0.01 hPa		
Noise	0.01 hPa RMS		
Sampling rate	25 Hz		

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Operating Parameters		
Communication	TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default	
	115,200)	
Power source	+ 3.2 to 5.2 V dc	
Power consumption	100 mW (typ)	
Operating temperature	-40 °C to +85 °C	
Mechanical shock limit	500 g (calibration unaffected)	
	1000 $g$ (bias may change), 5000 $g$ (survivability)	
Physical Specifications		
Dimensions	38 mm x 24 mm x 9.7 mm	
Weight	8 grams	
Enclosure material	Aluminum	
Regulatory compliance	ROHS, CE	
Integration		
Connectors	Data/power output: Samtec FTSH Series	
	(FTSH-105-01-F-D-K)	
Software	MIP Monitor, Windows XP/Vista/7/8/10 compatible	
Compatibility	Protocol compatibility across 3DM-GX3, GX4, RQ1,	
	GQ4, and GX5 product families	
Software development	MIP data communications protocol with sample code	
kit (SDK)	available (OS and platform independent)	



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