

## 3DM<sup>®</sup>-CX5-15 Inertial Measurement Unit (IMU)

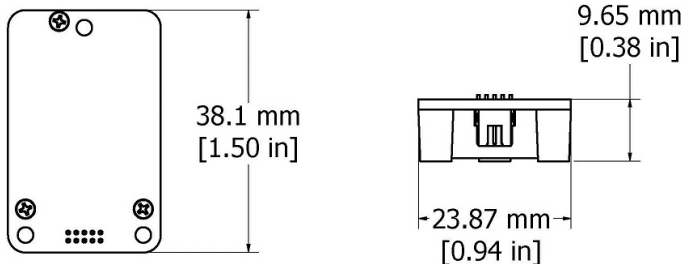


*3DM-CX5-15 – miniature, high-performance, industrial-grade inertial measurement unit (IMU) and vertical reference unit (VRU)*

The **LORD Sensing 3DM-CX5** family of high-performance, industrial-grade, board-level inertial sensors provide a wide range of triaxial inertial measurements and computed attitude and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration and angular rate, and are fully temperature-compensated and calibrated over the operating temperature. The use of Micro-Electro-Mechanical System (MEMS) technology allows for highly accurate, small, lightweight devices.

The LORD Sensing **MIP Monitor** software can be used for device configuration, live data monitoring, and recording. Alternatively, the **MIP Data Communications Protocol** is available for development of custom interfaces and easy OEM integration.



### PRODUCT HIGHLIGHTS

- Triaxial accelerometer, gyroscope, temperature sensors achieve the optimal combination of measurement qualities
- Dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic pitch and roll
- Smallest, lightest, highest performance IMU in its class

### FEATURES AND BENEFITS

#### BEST IN CLASS PERFORMANCE

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- Bias tracking, error estimation, threshold flags, and adaptive noise modeling allow for fine tuning to conditions in each application
- High-performance, low-drift gyros with noise density of 0.005°/sec/√Hz and VRE of 0.001°/s/g2RMS
- Accelerometer noise as low as 25 ug/√Hz

#### EASE OF USE

- User-defined sensor-to-vehicle frame transformation
- Easy integration via comprehensive and fully backwards-compatible communication protocol
- Robust, forward compatible MIP packet protocol

#### COST EFFECTIVE

- Out-of-the box solution reduces development time
- Volume discounts

### APPLICATIONS

- Platform stabilization, artificial horizon
- Health and usage monitoring of vehicles

# 3DM<sup>®</sup>-CX5-15 Inertial Measurement Unit (IMU)

## Specifications

General		
<b>Integrated sensors</b>	Triaxial accelerometer, triaxial gyroscope, and temperature sensors	
<b>Data outputs</b>	Inertial Measurement Unit (IMU) outputs: acceleration, angular rate, delta theta, delta velocity	
Inertial Measurement Unit (IMU) Sensor Outputs		
	Accelerometer	Gyroscope
<b>Measurement range</b>	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional)	300°/sec (standard) ±75, ±150, ±900° /sec (optional)
<b>Non-linearity</b>	±0.02% fs	±0.02% fs
<b>Bias instability</b>	±0.04 mg	8°/hr
<b>Initial bias error</b>	±0.002 g	±0.04°/sec
<b>Scale factor stability</b>	±0.03%	±0.05%
<b>Noise density</b>	25 µg/√Hz (2 g)	0.005°/sec/√Hz (300°/sec)
<b>Alignment error</b>	±0.05°	±0.05°
<b>Adjustable bandwidth</b>	225 Hz (max)	250 Hz (max)
<b>Offset error over temperature</b>	0.06% (typ)	0.04% (typ)
<b>Gain error over temperature</b>	0.03% (typ)	0.03% (typ)
<b>Scale factor non-linearity (@ 25°C)</b>	0.02% (typ) 0.06% (max)	0.02% (typ) 0.06% (max)
<b>Vibration induced noise</b>	--	0.072°/s RMS/g RMS
<b>Vibration rectification error (VRE)</b>	0.03%	0.001°/s/g <sup>2</sup> RMS
<b>IMU filtering</b>	Digital sigma-delta wide band anti-aliasing filter to digital averaging filter (user adjustable) scaled into physical units.	
<b>Sampling rate</b>	1 kHz	4 kHz
<b>IMU data output rate</b>	1 Hz to 1000 Hz	
Pressure Altimeter		
<b>Range</b>	-1800 m to 10,000 m	
<b>Resolution</b>	< 0.1 m	
<b>Noise density</b>	0.01 hPa RMS	
<b>Sampling rate</b>	25 Hz	

Computed Outputs	
<b>Attitude accuracy</b>	EKF outputs: ±0.25° RMS roll and pitch (typ) CF outputs: ±0.5° roll and pitch (static, typ) and ±2.0° roll and pitch (dynamic, typ)
<b>Attitude heading range</b>	360° about all axes
<b>Attitude resolution</b>	< 0.01°
<b>Attitude repeatability</b>	0.2° (typ)
<b>Calculation update rate</b>	500 Hz
<b>Computed data output rate</b>	EKF outputs: 1 Hz to 500 Hz CF outputs: 1 Hz to 1000 Hz
Operating Parameters	
<b>Communication</b>	USB 2.0 (full speed) TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200)
<b>Power source</b>	+4 to +36 V dc
<b>Power consumption</b>	500 mW (typ)
<b>Operating temperature</b>	-40°C to +85°C
<b>Mechanical shock limit</b>	500 g (calibration unaffected) 1000 g (bias may change), 5000 g (survivability)
Physical Specifications	
<b>Dimensions</b>	38 mm x 24 mm x 9.7 mm
<b>Weight</b>	8 grams
<b>Enclosure material</b>	Aluminum
<b>Regulatory compliance</b>	ROHS, CE
Integration	
<b>Connectors</b>	Data/power output: micro-DB9Samtec FTSH Series
<b>Software</b>	MIP Monitor, Windows XP/Vista/7/8/10 compatible
<b>Compatibility</b>	Protocol compatibility across 3DM <sup>®</sup> -GX3, GX4, RQ1, GQ4, GX5 and CV5 product families
<b>Software development kit (SDK)</b>	MIP data communications protocol with sample code available (OS and platform independent)