3DMGQ7 GNSS/INS
Magnetometer vs Dual-Antenna Heading in Fixed-Wing Aircraft
Motivation

Magnetometers are a common heading source for single antenna GNSS/INS fused sensors. Before using a magnetometer as a heading source, a hard and soft iron calibration must be completed after the device is installed in the vehicle. For fixed-wing aircraft, this is not only time consuming but also costly, especially for users of aircraft at busy airports with practice areas located far away.

This report compares the steps necessary to use magnetometer vs dual-antenna as a heading source for a Cessna 150M flown in a repeated flight profile.

Sensor

For this case study, two Parker-LORD, MicroStrain devices were used in testing, the 3DMGQ7 + 3DMRTK as seen below. The 3DMGQ7 (“GQ7”) is a dual-antenna, GNSS/INS navigation system that uses sensor fusion to provide high accuracy position and attitude estimates in challenging environments. The 3DMRTK is a network interface modem that provides plug-and-play RTK correction data to the GQ7.

Theory

At a high level, magnetometers measure the local magnetic field which consists of Earth’s magnetic field and any magnetic disturbances proximal to the sensor. To be used effectively in most applications, calibration must be completed to obtain accurate heading.

Dual-antenna heading uses two GNSS antennas mounted with a measured offset to calculate a “baseline” between the two antennas and a heading vector. It is inherently easier, requires no calibration and is immune to magnetic interference.
Installation

The GQ7’s antennas were securely mounted to the dash with a clear view of the sky and a baseline of 0.82m as shown in Figure 1. A PC running MicroStrain’s SensorConnect desktop application was secured in the aft baggage compartment and used to collect the data from the GQ7. The offset measurements were entered in SensorConnect.

Figure 1: Dual-Antenna Baseline

Test Procedure

Before employing the magnetometer as a heading source it must be calibrated. To calibrate, it must be mounted in the vehicle and pitched, and rolled to angles expected to be encountered during flight. For aircraft, steep turn maneuvering is not recommended at low altitude, nor allowed in certain types of airspace near airports, therefore this process can be time consuming and costly. For this case study, four flights were completed with different heading aiding sources:

- Data Collection with Uncalibrated Magnetometer
- Magnetometer Calibration
- Data Collection with Calibrated Magnetometer
- Data Collection with Dual-Antenna

For all four flights, the same procedure was executed to facilitate comparison:

1) Start recording
2) Takeoff and climb to 3000’
3) Fly away from airport to practice area for magnetometer calibration
4) Execute clearing turns and clear airspace of practice area for aircraft traffic
5) Complete two steep (60°) turns to facilitate calibration
6) Fly back to airport and land
7) Taxi to parking area, stop aircraft engine and chock wheels
8) Stop recording and review results

Looking east to Mt. Washington above Route 89 South, Jonesville, VT
Flight Event: Steep Turns

As mentioned in the Test Procedure, two steep turns were completed for each flight. The events of the steep turn are shown in the plots at left and highlighted by the numbered steps.

Steep Turn Procedure:
1. Raise wing, check left
2. Roll into 60° steep turn to left
3. Hold 60° bank angle for full 360° turn
4. Roll wings straight and level
(repeat steps 1-4 for right turn)
Conclusions

Magnetometer Heading:
• Calibration can be more costly in time and money than dual-antenna operation
• Useful for applications with low magnetic interference environments
• Calibration significantly improves heading measurements over un-calibrated case

Dual-Antenna Heading:
• Needs no calibration, only installation of antennas and measurement of their offsets
• Provides valid heading for the highest percent time